



1. Context : Towards Lenslesss Endoscopy



How to see neurons firing?

- \triangleright Image at microscale, in depth.
- \succ With the least invasivity.

Solution:

- \rightarrow Lensless endoscopy!
- Case of study [1] Single pixel detector → Core Wavefront Optics shaper (SLM)Imaged Fluorescence signal (biological) Highlighted point sample
- \triangleright SLM controls the light injected in each core of the MCF.
 - \triangleright The cores are aranged in a Golden Fermat's spiral [1].
 - \triangleright The light reflected/reemitted by the sample is integrated in a single-pixel detector.



- \triangleright The cores define a set Ω critical for the sensing \Leftrightarrow speckle illumination.
- \triangleright Far-field assumption: MCF diameter \ll Sample-Distal End distance.
- \triangleright Field-of-view \Leftrightarrow speckle illumination diameter \Leftrightarrow core mode field.



| 3. Interferometric structural models |
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| Low complexity model (LCM) in f LCM in \mathcal{I}_{Ω} |
| Spike model (I) Low-rankness |
| $\bar{f}(\boldsymbol{x}) = \sum_{i=1}^{K} \rho_i \delta(\boldsymbol{x} - \boldsymbol{x}_i) \text{ for } K \ll Q \qquad \qquad \boldsymbol{\mathcal{I}}_{\Omega}[\bar{f}] = \sum_i \rho_i \boldsymbol{u}(\boldsymbol{x}_i) \boldsymbol{u}^*(\boldsymbol{x}_i), \boldsymbol{u}(\boldsymbol{x})_j := e^{i2\pi \boldsymbol{p}_j^\top \boldsymbol{x}}$ |
| Sparsity in $\{\psi\}_{k=1}^d$ Sparsity in $\{\mathcal{I}_{\Omega}[\psi_k]\}_{k=1}^d$ |
| $\bar{f}(\boldsymbol{x}) = \sum_{k=1}^{d} \rho_k \psi_k(\boldsymbol{x}) \text{ with } \ \boldsymbol{\rho}\ _0 = K \ll d \qquad \qquad \boldsymbol{\mathcal{I}}_{\Omega}[\bar{f}] = \sum_{k \rho_k \neq 0}^{K} \rho_k \boldsymbol{\mathcal{I}}_{\Omega}[\psi_k]$ |
| Remark: \mathcal{I}_{Ω} is almost circulant $\Rightarrow \mathcal{I}_{\Omega} = C^* \mathcal{J} C$ with \mathcal{J} a circulant matrix. \Rightarrow Forward model = autocorrelative model to reduce computational cost |
| $y_m = oldsymbol{lpha}_m^* oldsymbol{\mathcal{J}} oldsymbol{\mathcal{C}} oldsymbol{lpha}_m = oldsymbol{eta}_m^* oldsymbol{\mathcal{J}} oldsymbol{eta}_m = (oldsymbol{eta}_m * oldsymbol{ar{eta}}_m) oldsymbol{F} oldsymbol{ar{f}}$ |
| (1) Reconstruction algorithm: given $\mathcal{B} = \mathcal{A} \circ \mathcal{T} \circ F$ |
| \blacktriangleright If f is discretised, and sparse in pixels, hope to solve the inverse problem with |
| $\hat{f} \in \operatorname{argmin}_{\boldsymbol{u}} \ \boldsymbol{u}\ _{1} \text{ s.t.} \ \underbrace{\boldsymbol{\mathcal{B}}(\boldsymbol{f}) + \boldsymbol{n}}_{\boldsymbol{y}} - \boldsymbol{\mathcal{B}}(\boldsymbol{u})\ _{1} \leqslant \epsilon $ (BPDN _{ℓ_1}) |
| (2) ℓ_2/ℓ_1 instance optimality of BPDN $_{\ell_1}$: given $K > 2k$, if: |
| ▷ for $k' \in \{K, K+k\}$, we have $\alpha_{k'} u _2 \le \mathcal{B}(u) _1 \le \beta_{k'} u _2$, $\forall k'$ -sparse u |
| \blacktriangleright and $\frac{1}{\sqrt{2}}\alpha_{k+K} - \beta_K \frac{\sqrt{k}}{\sqrt{2}} > \gamma > 0$, |

References

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Conclusion

Forward problem close to phase retrieval, interferometric model, but still linear in f.

 \succ LCM in f yields LCM in \mathcal{I}_{Ω} .

 \triangleright Potential for computational cost reduction.

 \triangleright Theoretical guarantees.

 \succ First experimental results \Rightarrow Proof of concept.

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